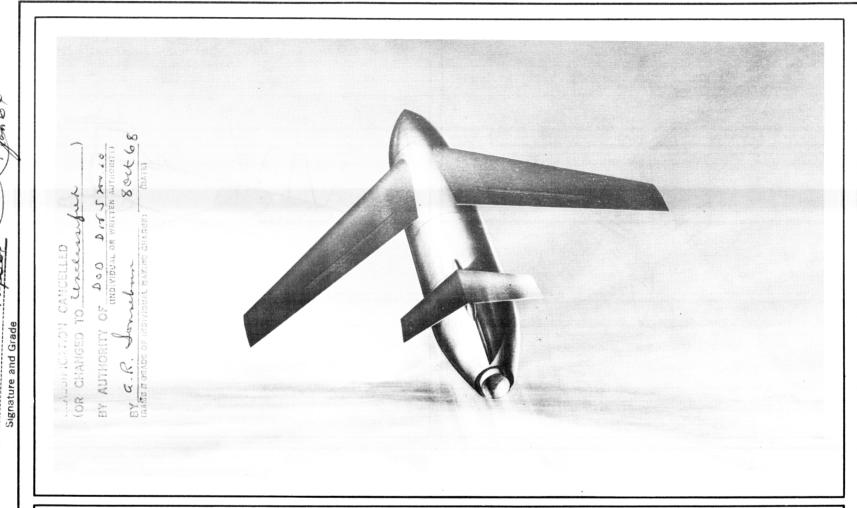
CG/Matador TM-61A+G/char

CONFIDENTIAL ONFIDENTIAL



# Standard Missile Characteristics

BY AUTHORITY OF THE SECRETARY OF THE AIR FORCE TM-61A & C -

MATADOR MARTIN ONE J33-A-37

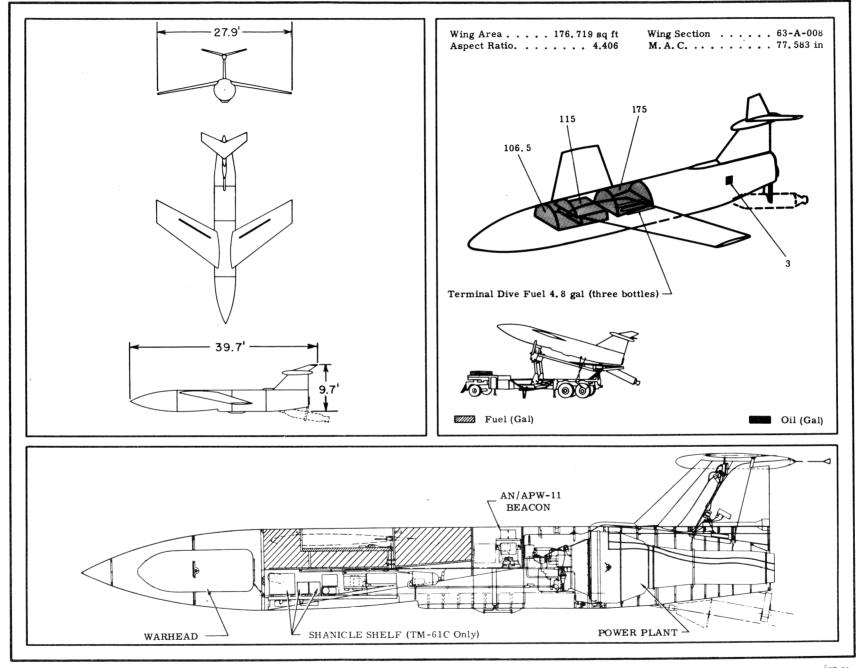
**ALLISON** 

4 SEP 56

CONFIDENTIAL

TM-61A & C

57WC-4984



#### **POWER PLANT**

| Nr. & Model.       (1) J33-A-37         Mfr       Allison         Engine Spec Nr       318-C         Type       Centrifugal         Length       159.5"         Diameter       49.3"         Weight (dry)       1790 lb |
|---|
| BOOSTER Nr. & Model (1) T-50 Mfr Picatinny Arsenal Engine Spec Nr   |

# **ENGINE RATINGS**

Weight (loaded) . . . . . . 1675 lb

| S. L. Static | LB   | - | RPM    | - | MIN  |
|--------------|------|---|--------|---|------|
| Max:<br>Mil: | 4600 | - | 11,750 | - | 5    |
| Nor:         | 4600 | - | 11,750 | - | Cont |

#### BOOSTER

S. L. Static LB - SEC

Nominal: 57,000 - 2.4

# Mission and Description

Navy Equivalent: None Mfr's Model: --The TM-61A and TM-61C are surface launched tactical missiles. The principal mission of these vehicles is the destruction of surface targets while under the direction of automatic guidance.

The configuration and aerodynamic characteristics of both vehicles are essentially identical. The Matador has a shoulder-type, swept wing and a "T" type tail. Use of honeycomb structures has made the construction of thin smooth contour surfaces for both the wing and tail possible. The fuselage is of monocoque construction with a flush type air inlet. The warhead is located in the nose section, while the guidance equipment is in the fuselage center section. The power plant is installed in the aft section of the vehicle and the automatically ejected booster rocket is installed externally in this section.

Lateral control is maintained by finger type spoilers located on the upper surface of the wing. An all movable stabilizer is employed for pitch control. The control system is of the electrical-hydraulic type. It is composed essentially of a Martin unattended gyro type stabilized autopilot whose principal of operation lies in the utilization of signals from displacement gyros and control surface position feedback. This system stabilizes the missile in pitch, roll and yaw. In addition, acceleration, climb and cruise phases are programmed and heading is adjusted in accordance with guidance signals. The guidance signals are furnished to the control system from either audio-modulated sources from AN/MSQ-1-AN/APW-11A radar or corrected commands from airborne SHANICLE equipment.

The significant difference of the TM-61C version from the TM-61A is the addition of SHANICLE hyperbolic mid-course guidance system equipment. The airborne components for the SHANICLE equipment are installed on a shelf in the fuselage center section.

# WEIGHTS

| Loading                                 | Lb                            |
|---|-------------------------------|
| Empty Design Launch 1st Motion Terminal | 12,748<br>13,593(A)<br>13,462 |
|   |                               |

(A) Actual

# F U E L

| Location Nr. Tanks Gal Fus, Ctr     |
|-------------------------------------|
| Grade JP-4 Specification MIL-F-5624 |
|                                     |
| OIL                                 |
| Fus, Aft                            |

# DIMENSIONS

| Wing Span 2           | 7.9' |
|-----------------------|------|
| Incidence             |      |
| Cathedral             |      |
| Sweepback (25% Chord) | 350  |
|                       | 9.7' |
| Height                | 9.7' |

#### GUIDANCE

- (a) INITIAL: Fixed bias pitch control plus programmed Air Speed control

  (b) MID-COURSE: MARC (AN/MSO-
- (b) MID-COURSE: MARC (AN/MSQ-1 radar track; AN/APW-11A air-borne beacon)(TM-61A)---MARC plus SHANICLE hyperbolic (TM-61C)
- (c) Programmed, semi-ballistic, zero-g dive CONTROL see Mission and Description block

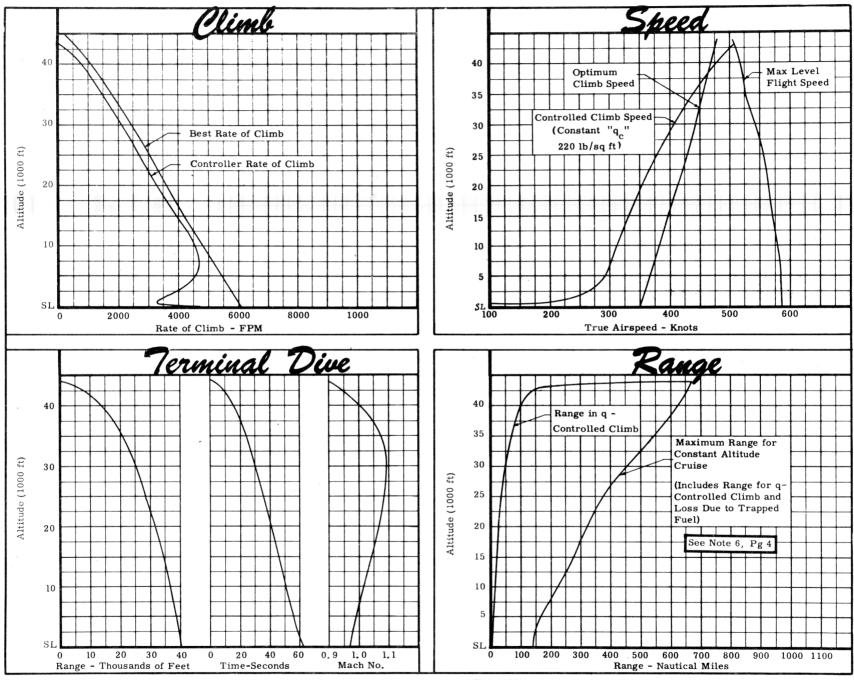
# LAUNCHING

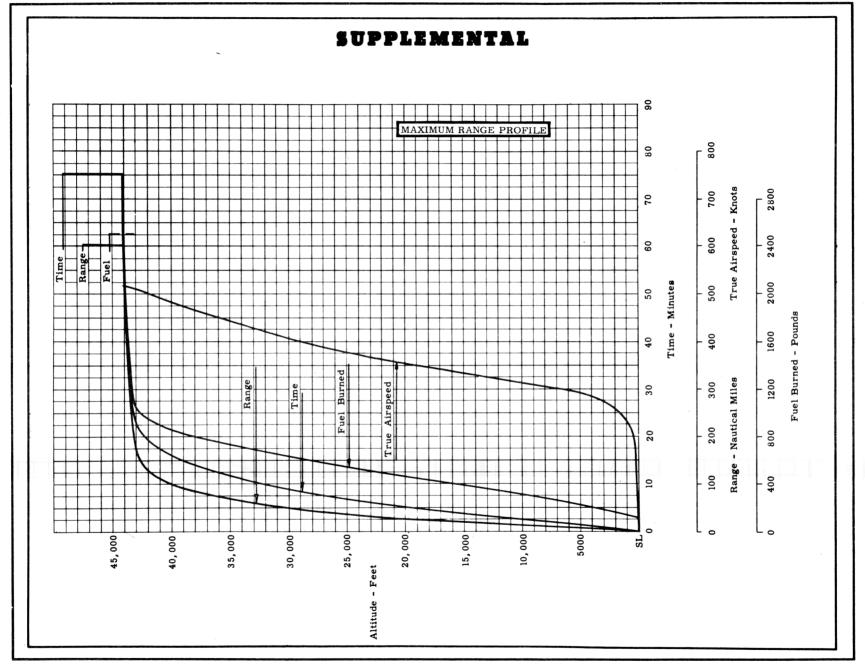
Launched from a mobile, "zero-length" launcher with solid rocket boost.

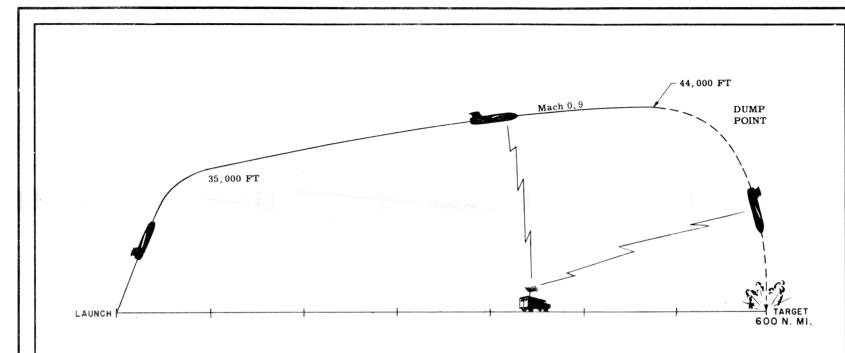
# WARHEAD

| Type General Purpose  |
|---|
| weight (lb) 3000  |
| FUZE  |
| General Purpose T1400 or T1402                              |
| or  |
| Special Airburst or Impact                                  |
| Electric Motor employed for arming any of above type fuzes. |

| AUNCH WEIGHT    Mathematical Part | C O N D I T I O N S ①   | DESIGN<br>MISSION  | NOTES  |
|-----------------------------------|---|--|--|
|                                   | Fuel (JP-4 6.5 lb/gal) (lb) Payload (lb) Payload (lb) Wing loading (lb sq/ft) Launching Distance (ft) Launching Time (sec) Initial Rate of Climb (ft/min) Initial Cruise Altitude (ft) Time to Climb to Cruise Altitude (min) Climb Distance (n. mi) RUISE ZONE Cruising Mach No./Speed (M/kn) Distance (n. mi) Final Altitude (ft) Gross Weight (lb) Terminal Altitude (ft) Distance (n. mi) Climb Distance (n. mi) Terminal Altitude (ft) Distance (n. mi) Climb Distance (Deg/Sec) Climpact Speed (Mach) Otal Range (4) | 13,593 2632 3000 77 0 2.4 4900 43,049 23 157 .89/512 443 44,200 9334 44,200 6.6 61 3 .97 600 | Pre-launch: Missile count down takes place at the launch site. External power is turned on for the last few minutes for check-out of controls and guidance. At X minus three minutes the engine is started and kept at idle (60% rpm) until X minus 30 seconds. Full military power is applied for the final 30 seconds of count-down.  Launch: The missile is launched from a zero-length launcher. Longitudinal control is maintained by a fixed bias pitch controller. When airspeed reaches 183 knots, an airspeed switch closes, introducing an airspeed system. Launchbias fades out over a period of approximately 100 seconds and an airspeed loop with a climb-cruise bias phase in. Directional gyro guides the missile in this phase.  Climb-Cruise: By the end of airspeed control change-over, the missile is at an altitude of about 5000 feet. Airspeed in climb is controlled by a fixed-reference dynamic pressure of 220 pounds per square foot. Since the system is non-integrating, the airspeed exceeds the fixed-reference figure up to approximately 44,000 feet, which is the trim altitude reached near end of mission. Overall guidance of the missile is assumed by either the MARC or SHANICLE systems during this phase of the mission. Terminal Dive: A transonic dive to target begins at a dump point indicated by the mid-course guidance system. Gyro precession varies so that lift will average zero throughout dive. An accelerometer loop senses and corrects for any divations from the prescribed zero-lift trajectory. At dive initiation the throttles reduced to idle, but a barometric override delays engine response until an altitude of approximately 15,000 feet is reached.  PERFORMANCE BASIS:  Calculated data based on Wind Tunnel data and Preliminary Flight Tests.  PERFORMANCE REFERENCE:  Glenn L. Martin Engineering Report 7371 dtd 15 Jun 1955.  REVISION BASIS:  To combine TM-61A and TM-61C brochures, revise characteristics, |







# GUIDANCE AND CONTROL-TM-61A

#### LAUNCHING PHASE

The missile is launched from a zero-length launcher. Longitudinal control is maintained by a fixed bias pitch controller. When airspeed reaches 183 knots an airspeed control system is phased into operation. The missile climbs under programmed airspeed control to an indicated dynamic pressure of approximately 220 lb/sq ft. The airspeed control period lasts until radar contact with the MARC guidance equipment for mid-course flight.

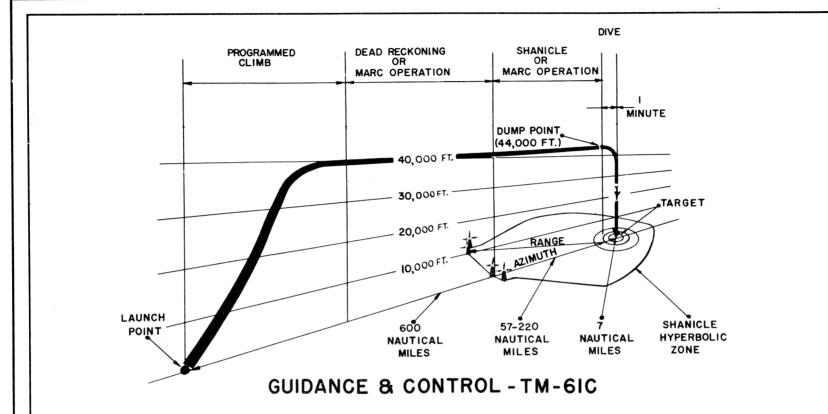
#### MID-COURSE FLIGHT

The TM-61A utilizes the MARC guidance system (Ground Radar Set AN/MSQ-1 and airborne Radar Set AN/APW-11A) for mid-course guidance. The AN/MSQ-1 ground based mobile equipment tracks the missile through the use of the airborne AN/APW-11A beacon. In addition, proper commands are developed either automatically or manually in the MSQ-1 equipment and sent over the radar link to the beacon and thence to the flight control system in order to control position.

#### TERMINAL DIVE

A semi-ballistic transonic dive begins at the "dump" point predicted by the MARC mid-course guidance equipment. When "dump" is signaled, the terminal dive system produces signal voltages which cause the engine to be throttled to idle, the warhead to start its fuzing operation, and the fuel system to be switched to terminal dive condition. Gyro precession with accelerometer corrections assures that the zero-lift trajectory is maintained until impact.

NOTE: Line-of-sight limitations to microwave propagation restricts the  $$TM\mbox{-}61A$$  with MARC guidance to 175 nautical mile range ahead of the  $AN/MSQ\mbox{-}1$  equipment.



#### LAUNCHING PHASE

The guidance mode for the launching phase is the same as for the TM-61A and lasts until a pre-determined point where one of three alternate mid-course guidance systems assumes control.

#### MID-COURSE PHASE

At the discretion of the launching agency, any one of three possible modes of mid-course guidance may be selected. The systems available are SHANICLE, MARC, or a combination of the two. If the SHANICLE hyperbolic system is employed for the mid-course, the missile is programmed into the SHANICLE zone. Four base stations (consisting of antenna towers and transmitting equipment) generate two families of LORAN-type constantime differential hyperbolic signals; one family for azimuth guidance, and

one family for range guidance. Airborne equipment measures the time of arrival of these signals and issues corrective commands to the controls in the missile. The missile is guided along the azimuth hyperbola until it crosses the intersecting range hyperbola, at which time the terminal dive is initiated. If the MARC system is selected, the missile is controlled from the ground based mobile transmitter until arrival at the dump point or may be flown into the SHANICLE zone where the SHANICLE system assumes control until terminal dive. While operating under SHANICLE guidance the missile emits no signal.

#### TERMINAL DIVE

The terminal dive phase is conducted in the same manner as the TM-61A.

REVISION BASIS: Data recoordinated this date.